

DYNAMICS OF MACHINE (LAB)

General Course Information

Course Code: PCC-ME305-P	Course Assessment Methods (internal: 30; external:
Course Category: Professional Core Course	70): Internal practical evaluation is to be done by the
Course Credits: 1.0	course coordinator. The end semester practical
Mode: Practical	examination will be conducted jointly by external and
Contact Hours: 02 hours per week	internal examiners

Course Outcomes

Sr. No.	Course Outcome				
		Level			
CO1	Students will be able to define the various mechanical systems like flywheel, transmission	L1			
	drives, governor, gyroscope, brake, dynamometer, balancing.				
CO2	Students will be able to describe different mechanical systems through models and experimental setups.	L2			
CO3	Students will be able to solve different kind of problems related to force analysis in different mechanical systems experimentally.	L3			
CO4	Students will be able to analyse dynamically and determine the parameters involved in the various mechanical systems experimentally.	L4			
CO5	Students will be able to select and design appropriate mechanical system required for a particular application.	L5			

Experiments in DOM Lab

- 1. To perform experiment on Watt Governor, to Prepare Performance Characteristic Curves, and to find stability and sensitivity.
- 2. To Perform Experiment on Porter Governor, to Prepare Performance Characteristic Curves, and to Find Stability and Sensitivity.
- 3. To Perform Experiment on Proell Governor, to Prepare Performance Characteristic Curves, and to Find Stability and Sensitivity.
- 4. To Perform Experiment on Hartnell Governor, to Prepare Performance Characteristic Curves, and to Find Stability and Sensitivity.
- 5. To Study Gyroscopic Effects Through Models.
- 6. To Determine Gyroscopic Couple on Motorized Gyroscope.
- 7. To Perform the Experiment for Static Balancing on Static Balancing Machine.
- 8. To Perform the Experiment for Dynamic Balancing on Dynamic Balancing Machine.
- 9. To study the working of multiplate clutch.



10. To Find BHP of an Engine Using Rope Brake Dynamometer.

Course Articulation Matrix (CO to PO/PSO Mapping)

	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	1	1	1								3	3		_
CO2	3	2	1	1						2		3	3		
CO3	3	3	2	1	1				1	2		3	3		
CO4	3	3	2	2	1			1	2	2		3	3	1	1
CO5	3	2	3	2	2			1	2	2		3	3	2	3

1: (Slight/Low),

2:(Moderate/Medium),

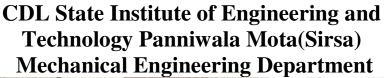
3:(Substantial/High)

Sr. No.	Name of equipment	Qty	Mo
1.	Watt Governor Set up	01	Built In house:
2.	Porter Governor	1829	Combined
3.	Proell Governor		Universal Governor set
4.	Hartnell Governor		up.
5.	Hartnell Governor		
6.	Motorized Gyroscope Apparatus	01	Built In house
7.	Static and Dynamic Balancing Machine	01	Built In house
8.	Multiplate clutch model	01	Built In house
9.	Rope Brake Dynamometer Setup	01	Built In house





DOM Lab





Universal Governor Apparatus



Gyroscope Apparatus





Static & Dynamic Balancing Apparatus



Cut Out working model of Differential



Prony brake instrument





Rope Brake Dynamometer Inclined Plane Apparatus



Clutch Model